

RPG200 Pirani Vacuum Gauge

Introduction

The Series RPG200 Pirani vacuum gauge offers a wide measurement range from atmosphere to medium and high vacuum. This Pirani transducer features good accuracy and excellent long-term stability. In addition, it is high performance-price ratio.

The Series Pirani vacuum gauge is a thermal conductivity gauge based on MEMS Pirani chip. The chip is manufactured using microfabrication technology, resulting in excellent accuracy and consistency. It also integrates a temperature sensing circuitry, featuring good sensitivity and repeatability. Compared to the filament Pirani gauges, it is more resistant to contaminants.

The Series Pirani vacuum gauge has analog signal output and RS485 digital communication interface. It can be compatible with vacuum gauges from other manufacturers, allowing for plug-and-play without system adjustments or hardware interface changes. As a result, the previously accustomed output curves can be directly obtained.

The Series Pirani vacuum gauge can also output other standard industrial signals according to the customer application requirements.



Features

- Range from 5×10^{-4} mbar to 1000 mbar
- Good accuracy and repeatability
- Adjustable output curve
- More resistant to contamination due to low operating temperature
- With temperature compensation
- High performance-price ratio

Applications

- Freeze dryer control
- Mass spectrometer control
- Foreline and roughing pressure measurement
- Low-temperature gas cylinders, gas tanks
- Heat treatment / Vacuum furnace
- System process control

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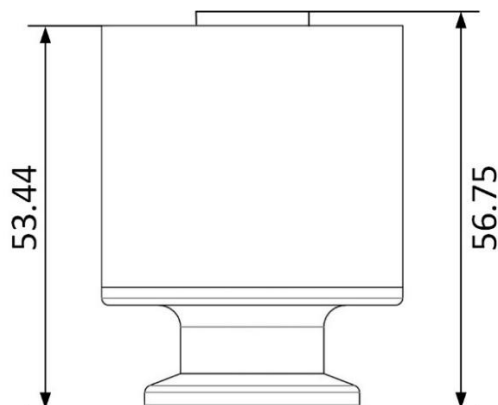
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1. Specifications

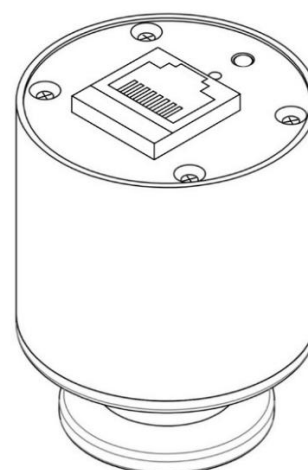
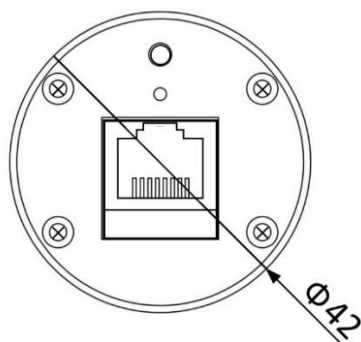
(Accuracy and repeatability are typical values measured with N₂ gas at ambient temperature after zero adjustment)

Parameter	Min.	Typ.	Max.	Units	Conditions
Sensor Type	MicroPirani (MEMS Thermal Conductivity)				-
Measurement range	5x10 ⁻⁴		1000	mbar	N ₂ /Air
Output voltage	1.9		10	V	Standard model or Factory settings
Output curve	Logarithmic curve				
Accuracy		±10%		mbar	5x10 ⁻⁴ ~ 1x10 ⁻³
		±5%		mbar	1x10 ⁻³ ~ 100
		±25%		mbar	100 ~ 1000
Resolution		16		bit	
Repeatability		±2%		Reading	1x10 ⁻³ ~ 100mbar
Response time		0.1		s	
Supply voltage	9	24	30	V	
Operating current		30		mA	
Identification		27		KΩ	Factory settings
Operating temperature	0		40	°C	
Storage temperature	-20		65	°C	
Overpressure limit			6	bar	
Probe material	304 stainless steel				Factory settings

2. Dimensions



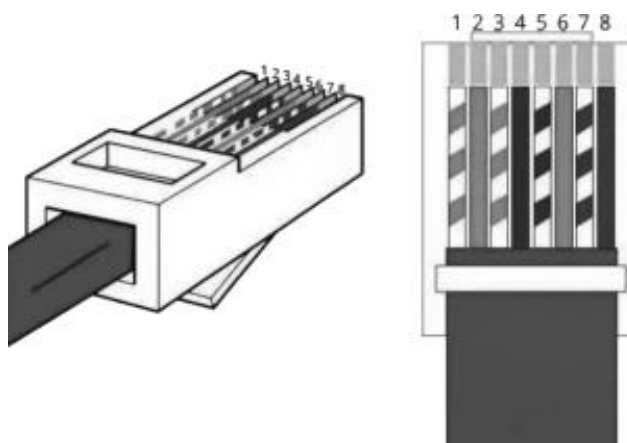
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3. Pin assignment

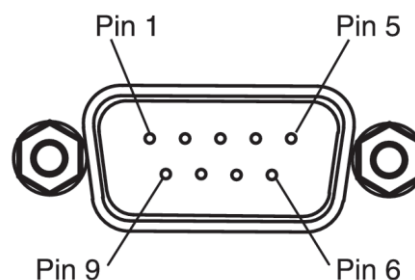
3.1. RJ45 8-pin

Pin1	Power + (9~30VDC)
Pin2	Power GND
Pin3	Analog signal output
Pin4	27K Ω identification
Pin5	Analog Signal GND
Pin6	NC
Pin7	RS485, DATA-
Pin8	RS485, DATA+



3.2. D-Sub 9-pin

Pin1	Relay NO
Pin2	Relay NC
Pin3	Power + (9~30VDC)
Pin4	Power GND
Pin5	Analog Signal Output
Pin6	Relay Common
Pin7	RS485, DATA-
Pin8	Analog Signal GND
Pin9	RS485, DATA+



4. Digital Signal Output

The product adopts the standard Modbus RTU protocol. The default communication parameters are as follows:

- Default address: 255 (0xFF)
- Baud Rate: 9600
- Data Bits: 8
- Stop Bits: 1
- Parity: None

4.1. Register Types

The series uses the holding register in Modbus RTU to read the air pressure value and set the Modbus address of the sensor. The default Modbus address bit for sensor is 255.

4.2. Holding Register Function Definitions

Holding register (read/write) Code: 03		
Modbus address	Description	Data Type
0x0000	1. Stores air pressure value, unit Pa. To convert to actual air pressure value, divide by 1000. 2. Big-endian storage (high-order byte stored at low-order address, low-order byte stored at high-order address) 3. Example: If the read value is 0x05F5E100, the converted air pressure value is 100000Pa	32-bit integer
0x0001		
0x0005	1. Store sensor manufacturing year and month information 2. Example: If the read value is 0x1904, the sensor was manufactured in April 2025	16-bit unsigned integer
0x0006	1. Stores sensor production batch and Modbus address information. 2. Example: If the read value is 0x0104, the sensor was produced in the first batch in April 2025, and the factory-set Modbus address information address is 04 3. The sensor's default Modbus address is 0xFF, i.e., 255.	16-bit unsigned integer

4.3. Communication Examples

1. Write sensor address (use function code 10 to change address, function code 06 is not supported)

Instruction	Slave address	Function code	Register start address high eight bits	Register start address low eight bits	Number of registers high eight bits	Number of registers low eight bits	Number of bytes	Data4	Data3	Data2	Data1	CRCL	CRCH
Example	0xFF	0x10	0x00	0x05	0x00	0x02	0x04	0x00	0x00	0x00	0x01	0xC5	0xBB

Note: Data1 is the device's Modbus bus address.

Slave response:

Instruction format	Slave address	Function code	Register start address high eight bits	Register start address low eight bits	Number of registers high eight bits	Number of registers low eight bits	CRCL	CRCH
Example	0xFF	0x10	0x00	0x00	0x00	0x02	0x54	0x16

Note: No information to be parsed in the slave response

2. Reading Air Pressure Value (Using Function Code 03)

Master Sends Command:

Instruction format	Slave address	Function code	Register start address high eight bits	Register start address low eight bits	Number of registers high eight bits	Number of registers low eight bits	CRCL	CRCH
Example	0xFF	0x03	0x00	0x00	0x00	0x02	0xD1	0xD5

Note: 0xFF is the device's general address. If the device's Modbus bus address is known, it can be used directly.

Slave response:

Instruction format	cockpit Address	Function code	Return Number of bytes	Data4	Data3	Data2	Data1	CRCL	CRCH
Example	0xFF	0x03	0x04	0x00	0x01	0x00	0x05	0xC1	0xD7

Where 00 01 00 05 is the air pressure data, with the most significant byte first and the least significant byte last. 00 01 00 05H is 65541 in decimal. Actual air pressure value = 65541 * 0.001 = 65.541 (Pa).

5. Analog Signal Output

The analog signal output can be remotely transmitted to external devices such as PLCs, DCS systems, and recorders. The voltage output range is adjustable. The typical vacuum degree and analog signal correspondence are shown below.

5.1. Output Voltage and Formula 1

$$P = 10^{\frac{U-c}{1.286}}$$

Where:

U —Voltage output

P —Different vacuum degree units

c —Constant used for different vacuum degree units, as shown in the table below:

U	P	c
V	mbar	6.143
V	Torr	6.304
V	mTorr/micron	2.448
V	Pa	3.572

5.2. Output Voltage and Formula 2

$$P = 10^{U-c}$$

Where:

U —Voltage output

P —Different vacuum degree units

c —Constant used for different vacuum degree units, as shown in the table below:

U	P	c
V	mbar	6
V	Torr	6.125
V	mTorr/micron	3.125
V	Pa	4

5.3. Output Voltage and Formula 3

$$P = 10^{U-c}$$

Where:

U —Voltage output

P —Different vacuum degree units

c —Constant used for different vacuum degree units, as shown in the table below:

U	P	c
V	mbar	5.5
V	Torr	5.625
V	mTorr/micron	2.625
V	Pa	3.5

5.4. Output Voltage and Formula 4

$$P = 10^{U-c}$$

Where:

U —Voltage output

P —Different vacuum degree units

c —Constant used for different vacuum degree units, as shown in the table below:

U	P	c
V	mbar	5
V	Torr	5.125
V	mTorr/micron	2.125
V	Pa	3

5.5. Output Voltage and Formula 5

$$P = 10^{U-c}$$

Where:

U —Voltage output

P —Different vacuum degree units

c —Constant used for different vacuum degree units, as shown in the table below:

U	P	c
V	mbar	5.875
V	Torr	6
V	mTorr/micron	3
V	Pa	3.875

6. Calibration

The vacuum gauge is calibrated at the factory, but due to vibration during transportation or contamination during long-term operation, the vacuum gauge may drift. If a large deviation in the vacuum gauge measurement value is found, zero-point and full-scale calibration can be performed. In addition, the thermal conductivity of gas under medium and high vacuum is related to the type of gas. Different types of gases have different thermal conductivity coefficients for the sensor. The vacuum gauge is calibrated with standard nitrogen at the factory. Therefore, when measuring the vacuum of gases other than air or nitrogen, the sensor needs to be calibrated by the original manufacturer.

6.1. Zero-Point Calibration

Install the vacuum gauge on the vacuum system, preferably in the same environment as the vacuum gauge. Power on the vacuum gauge to preheat it and run it continuously. At the same time, evacuate the vacuum system to below 0.0001Pa and wait for 5 minutes. When the vacuum gauge reaches thermal equilibrium, zero-point calibration can be performed. The specific operation is as follows.

- Insert a pin into the zeroing and full-scale adjustment holes, press and hold the button until the red light illuminates, then release the button;
- Press the button briefly once. The red light will flash 3 times and then turn off;
- The indicator light will automatically return to a solid green state. At this point, the vacuum gauge zeroing operation is complete and it is ready for normal operation.

6.2. Full-scale calibration

Power on the vacuum gauge under atmospheric pressure to preheat it. It is best to do this under the same environment as the vacuum gauge is used in, and wait 5 minutes until the vacuum gauge reaches thermal equilibrium. Then, the full-scale calibration operation can be performed. The specific operation is as follows:

- Insert a pin into the zeroing and full-scale adjustment holes, press and hold the button until the red light illuminates. Continue pressing the button until the green light illuminates, then release the button;
- Press the button briefly once. The green light will flash 3 times and then turn off;
- The indicator light will automatically return to a solid green state. At this point, the vacuum gauge full-scale calibration operation is complete and it is ready for normal operation.

7. Indicator Light Status Description

Solid green light – Vacuum gauge is in normal working condition.

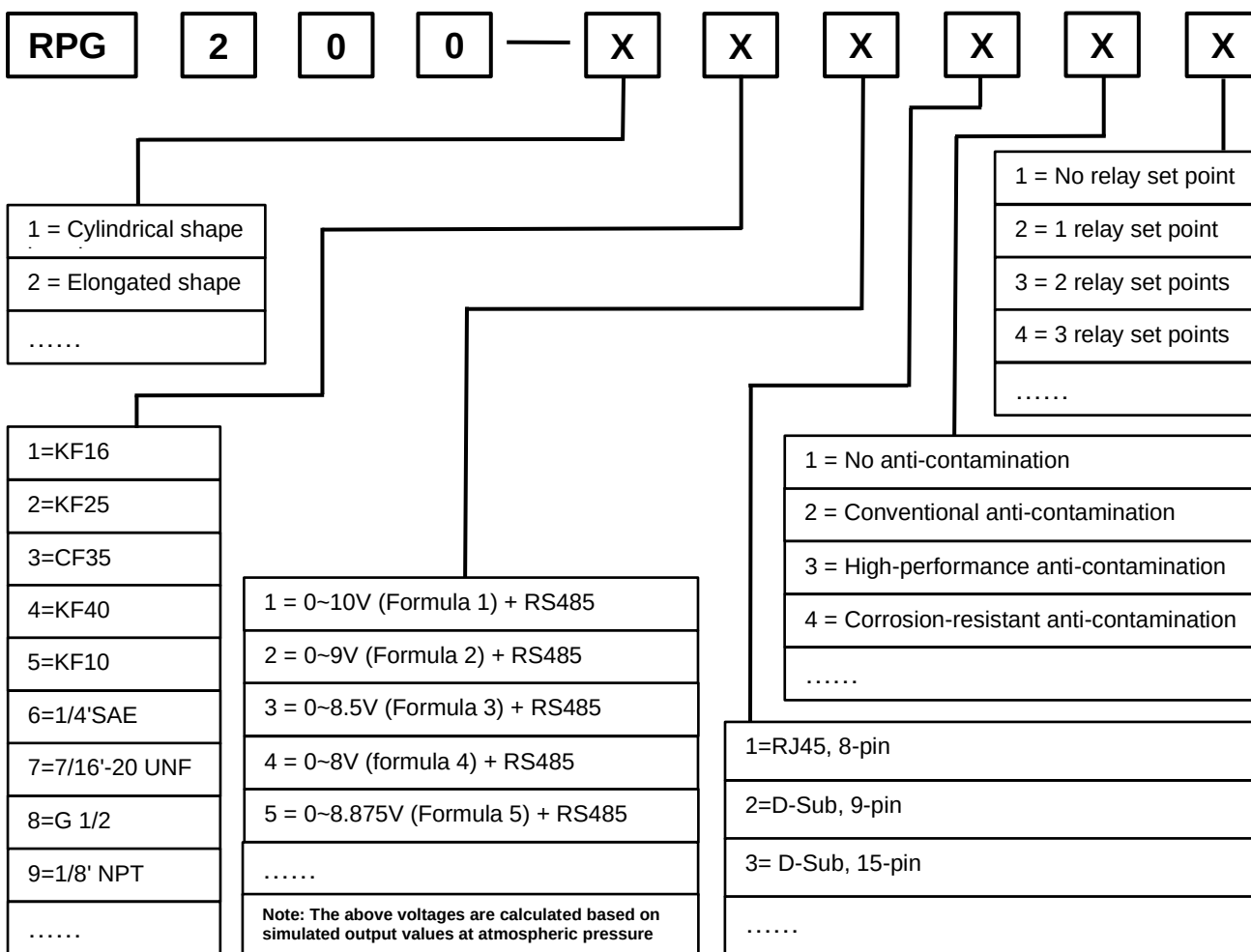
Red light is always on—the vacuum gauge is malfunctioning, and the processing circuit MCU has not entered normal working state.

Indicator light off – Vacuum gauge power supply abnormal.

Red light flashes 3 times – Vacuum gauge completes zero-point calibration.

Green light flashes 3 times – Vacuum gauge completes full-scale calibration.

8. Ordering Information



The standard model of this series of Pirani vacuum gauges is RPG200-111121. If there are other non-standard models, please consult with RQ for definition.

9. Revision History

Product Datasheet Version Control (RPG200)			
Version	Modification Time	Modification Content	Modifier
V1.0	2022.11	Initial Version	YSC
V2.0	2023.11	Optimized Product Appearance and Analog Signal Output	YSC
V3.0	2024.01	Optimized Analog Signal Output and Ordering Information	YSC
V4.0	2024.02	Optimized Calibration Instructions and Indicator Light Status	YSC
V5.0	2024.06	Optimized Ordering Information	YSC
V6.0	2026.01	Optimized Analog and Digital Output Information	YSC

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